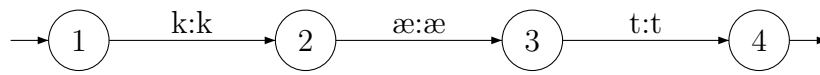
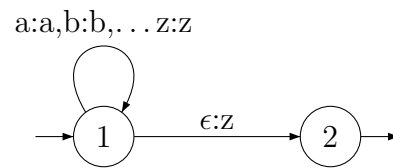


Transducer L:



Transducer P:



Calculate $L \circ P$ and $P \circ L$.